

Introduction to proximal causal inference

Non-parametric and parametric methods

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Known but unmeasured confounder

We never believe conditional exchangeability holds.



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How to survive in the presence of known unmeasured confounders?

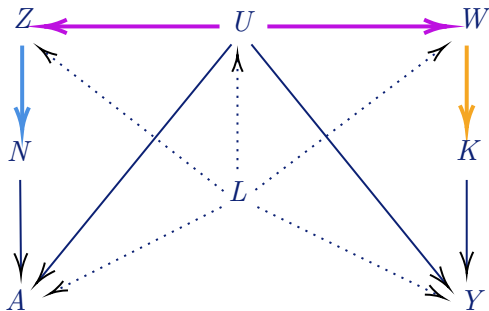
Proximal causal inference helps! ... but where does it come from?

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it come from?

Let's first take a glance and then see how it's
formulated...

First glance at proximal causal inference

Proximal causal inference strategy is dedicated to deal with such situation: a (set of) KU- (known but unmeasured) confounder(s). ATE can be point-identified upon considering a treatment-side proxy Z and an outcome-side proxy W , with additional assumptions.



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We need more information and alter our assumption sets!

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KU-confounder is, nevertheless, easier to deal with compared to a unknown-and-unmeasured confounder. There are already alternatives for a (set of) UU-confounder(s) when conditional exchangeability doesn't hold:

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- Instrument variable?
- Negative (population/outcome) control?
- Front door formula (causal mediation)?
- ...

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- **NOT** considering the “known” information for a KU-confounder; and are
- adding new **strict assumptions** (e.g. modelling assumptions and rank preservation in NC methods) [1], or
- altering the underlying population (e.g. monotonicity assumptions in NC/IV methods)

Alternatives to “KU-confounder”

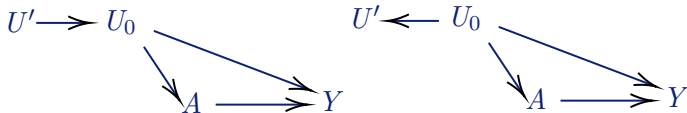
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We therefore want another approach that integrates available information of “the known part” and does not add strong restrictions / strict assumptions that we don't believe either.

Proxy-based thinking

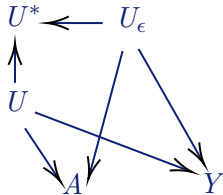
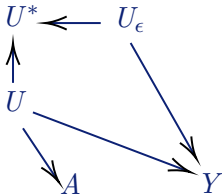
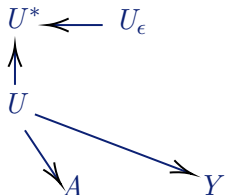
- When data for a confounder U_0 is not available, a natural alternative is to consider one measured proxy [2] of it, U' ;
- Intuitively, if $U' \propto U_0$ and U' is strictly only associated with U_0 , the average treatment effect (ATE) can be point identified without additional assumptions.



Proxy-based thinking

- However, we can never have a perfect proxy, otherwise it's equivalent to know everything about U_0 .
- The actual proxies come with noises and lose information carried by the targeted confounder;
- Without additional **assumptions** a proxy may only mitigate but never eliminate bias [3];
- Error generating mechanism from targeted confounder to proxy is extremely important [2], e.g. coarsening, mismeasurement, etc.

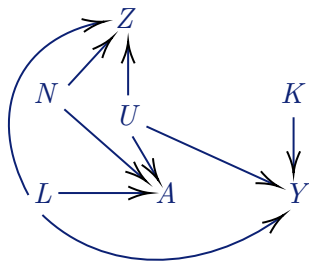
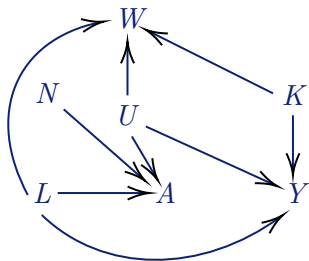
Mismeasured variable as proxies



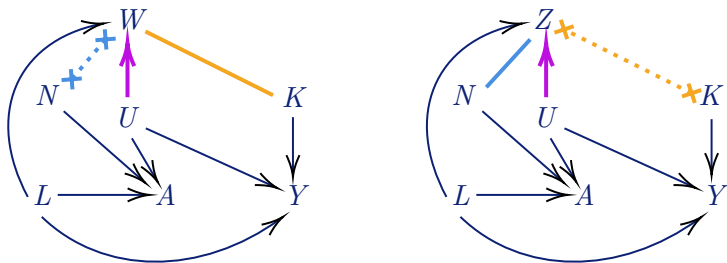
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Approaching proxy-based inference (I)

- Negative control (NC) exposure (NC/e) and NC outcome (NC/o) are two most used proxy-based strategies.
- NC/o requires a proxy W that is U -comparable to Y but not caused by A or sharing a common cause [4];
- NC/e requires a proxy Z that is U -comparable to A but not causing Y or sharing a common cause [4].



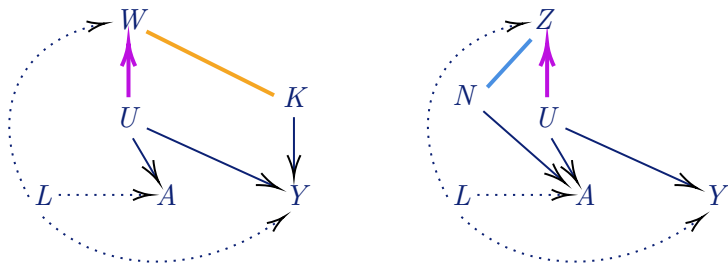
Approaching proxy-based inference (I)



Left: NC/o proxy; proxy W is similar enough to Y , except that it is not caused by A or share common causes;

Right: NC/e proxy; proxy Z is similar enough to A , except that it cannot cause Y or share common causes.

Approaching proxy-based inference (I)

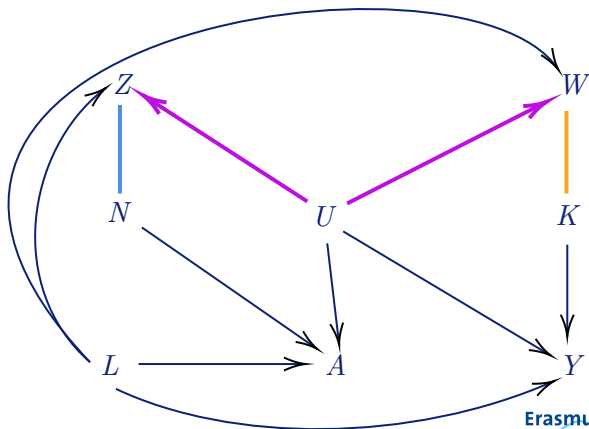


Left: NC/o proxy; proxy W is a child of U , and is (only) d-connected with Y ;

Right: NC/e proxy; proxy Z is a child of U , and is (only) d-connected with A .

Approaching proxy-based inference (II)

Upon combining both the NC/o- and NC/e-proxies, we get...

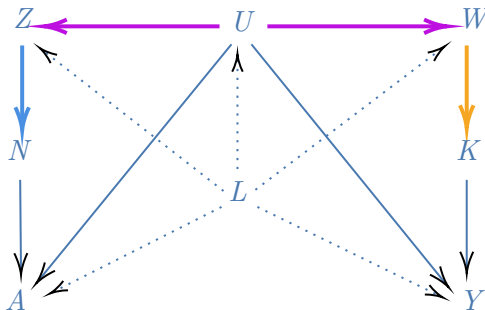


Approaching proxy-based inference (II)

And after some rearrangement, we get our final DAG...

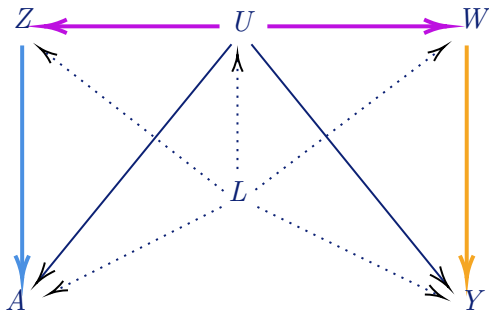
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Nonparametric Identification (I)

Given observed individual level data with a binary treatment

$$\mathcal{O}_i = \langle Y_i, A_i, \mathbf{L}_i, Z_i, W_i \rangle,$$

an ATE $\psi = \mathbb{E}[Y^{a=1} - Y^{a=0}]$ is nonparametrically identified

without the presence of U , if standard identifiability conditions

A1 through **A3** hold:

A1 Consistency: $Y_i^a = Y_i \quad \forall a, \quad a.s.$

A2 Treatment positivity over $\langle \mathbf{L}, Z, W \rangle$:

$$\Pr[A = a | \mathbf{L}, Z, W] > 0 \quad \forall a, \quad a.s.$$

A3 Exchangeability over $\langle \mathbf{L}, Z, W \rangle$: $Y^a \perp\!\!\!\perp A | (\mathbf{L}, Z, W) \quad \forall a$

Nonparametric Identification (I)

With KU-confounders U_i , **A3** does not hold, and ATE cannot be identified given \mathcal{O}_i and **A1-2**.

Proximal causal inference nonparametrically identifies ATE if additional conditions hold [1]:

A4 Independence of Y and Z : $Z \perp\!\!\!\perp Y | (A, \mathbf{U}, \mathbf{L})$

A5 Independence of W and A , W and Z : $W \perp\!\!\!\perp (Z, A) | (\mathbf{U}, \mathbf{L})$

A6 Exchangeability over $\langle \mathbf{L}, \mathbf{U} \rangle$: $Y^a \perp\!\!\!\perp A | (\mathbf{U}, \mathbf{L}) \quad \forall a$

A7 Treatment positivity over $\langle \mathbf{L}, \mathbf{U} \rangle$:

$$\Pr[A = a | \mathbf{L}, \mathbf{U}] > 0 \quad \forall a, \quad a.s.$$

A8 Statistical completeness for \mathbf{U} given Z :

$$\mathbb{E}[g(\mathbf{U}) | Z, A = a, \mathbf{L} = \mathbf{l}] = 0 \quad a.s. \Leftrightarrow g(\mathbf{U}) = 0, \quad \forall a, \mathbf{l}, \text{ and a square-integrable function } g$$

G-formula (II)

Suppose there exists an function $h = h(w, a, l)$ that solves the equation a.s.:

$$\mathbb{E}[Y|A, Z, L] = \int h(w, A, L) dF(w|A, Z, L)$$

then if **A1-2**, **A4-8** holds, ATE is nonparametrically identified by:
(outcome-side proximal g-formula)

$$\psi = \int_{\mathcal{L}} \int \left[h(w, a = 1, l) - h(w, a = 0, l) \right] dF(w|l) dF(l)$$

G-methods are all compatible and can be used for estimation.

G-formula (II)

Assumption **A9** suffices for the existence of such a “bridge” function $h = h(w, a, l)$:

A9 Statistical completeness for Z given W :

$$\mathbb{E}[g(Z) | W, A = a, L = l] = 0 \text{ a.s.} \Leftrightarrow g(Z) = 0, \quad \forall a, l, \text{ and a square-integrable function } g$$

G-formula (II)

Note: There are alternatives to completeness assumptions **A9** and/or **A8** upon considering different “flows of information” and starting points [5].

With $U|W$ completeness (alternative to **A8**) and $W|Z$ completeness (alternative to **A9**), a treatment bridge function $q = q(z, a, l)$ is valid, and ATE is identified by:
(treatment-side proximal g-formula)

$$\psi = \int_{\mathcal{L}} \int (-1)^{1-a} q(z, a, l) y \, dF(y, z, a|l) \, dF(l)$$

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Parametric assumptions

Two-stage least squares (2SLS) are implemented the most for parametric estimation of an ATE via proximal causal inference approach.

Given that assumptions **A1**, **A4-6** hold, and that no structural violation of treatment positivity over $\langle \mathbf{L}, \mathbf{U} \rangle$, with additional parametric assumptions:

$$\mathbf{P1} \quad \mathbb{E}[Y^a | A, Z, L, U] = \beta_0 + \beta_a A + \beta_l L + \beta_u U;$$

$$\mathbf{P2} \quad \mathbb{E}[W | A, Z, L, U] = \alpha_0 + \alpha_l L + \alpha_u U$$

Parametric estimation

P1 and **P2** can be rewritten as:

$$\mathbb{E}[Y^a|A, Z, L, U] = \beta_0 + \beta_a A + \beta_l L + \beta_u U \Rightarrow$$

$$\mathbb{E}[Y^a|A, Z, L] = \beta_0 + \beta_a A + \beta_l L + \beta_u \mathbb{E}[U|A, Z, L];$$

$$\mathbb{E}[W|A, Z, L] = \alpha_0 + \alpha_u \mathbb{E}[U|A, Z, L] + \alpha_l L \Rightarrow$$

$$\mathbb{E}[U|A, Z, L] = -\alpha_u^{-1} \alpha_0 - \alpha_u^{-1} \alpha_l L + \alpha_u^{-1} \mathbb{E}[W|A, Z, L];$$

\Rightarrow

$$\mathbb{E}[Y^a|A, Z, L] = (\beta_0 - \beta_u \alpha_u^{-1} \alpha_0) + \beta_a A + (\beta_l - \beta_u \alpha_u^{-1} \alpha_l) L$$

$$+ \beta_u \alpha_u^{-1} \mathbb{E}[W|A, Z, L]$$

$$= \beta_0^* + \beta_a^* A + \beta_u^* \mathbb{E}[\hat{W}|A, Z, L] + \beta_l^* L$$

Parametric estimation

An ATE is then parametrically identifiable through a 2SLS approach [6], estimated by the coefficient β_a^* in a 2SLS regression:

$$\begin{aligned}\mathbb{E}[Y^a | A, Z, L, \hat{W}; \beta] &= \beta_0^* + \beta_a^* A + \beta_u^* \mathbb{E}[\hat{W} | A, Z, L] + \beta_l^* L \\ \mathbb{E}[W | A, Z, L; \alpha] &= \alpha_0^* + \alpha_a^* A + \alpha_z^* Z + \alpha_l^* L + \epsilon_w\end{aligned}$$

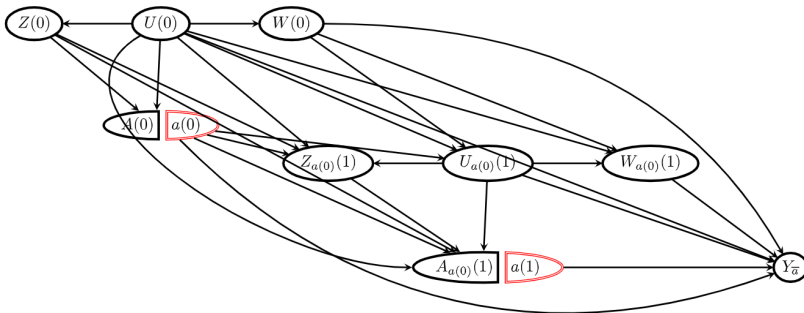
Note: Statistical and modelling constraints/assumptions (e.g. distribution; the existence of MGF for error term, etc.) apply for different types of Y and W . This approach can be generalized in the presence of effect measure modification [7].

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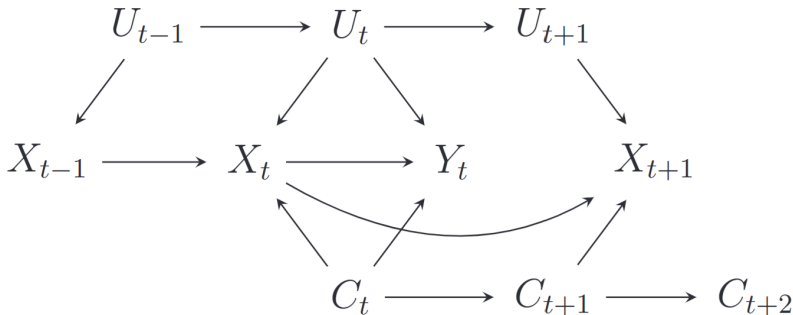
Time-varying settings

Sequential proxies can be used in a time-varying setting to allow that sequential exchangeability assumption over L not hold [7]:



Time-varying settings

Future exposures and past outcomes can serve as valid proxies [8]:



Closing and take-home message

- 1 PCI deals with **KU**-confounders.
- 2 PCI has its root in **measurement error**-based thinking and **proxy**-based approaches.
- 3 PCI combines **negative control** outcome and exposure proxy.
- 4 PCI makes the use of the residual information carried by measured proxies around the unmeasured things.
- 5 Nonparametric estimation of ATE via PCI is flexible and requires additional statistical assumptions (completeness); 2SLS can be used for parametric estimation.
- 6 Finding valid proxies is challenging. Mismeasured versions, future exposures, and past outcomes can sometimes serve as proxies.

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Thanks!

